## LESSON PLAN

**SUB: ENERGY CONVERSION - II** 

BRANCH:- ELECTRICAL ENGG.

SEMESTER: 5th

SESSION:2022-2023

NAME OF FACULTY: NIBEDITA HO



## GOVERNMENT POLYTECHNIC, BHADRAK

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G.P.BHADRAK

Academic Co-brdinator

Principal Principal Principal Govt. Polytechnic, Bhadrake Govt. Polytechnic

Discipline: Electrical Engg.	Semester: 5 <sup>th</sup>	Name of the Teaching Faculty : Nibedita Ho
Subject: Energy Conversion - II	No. of Days/per week class allotted:4	Semester from date: 15.09.2022 To Date: 21.01.2023  No. of Weeks:15
Week	Class Day	Theory
1 <sup>st</sup>	131	Basic working principle of alternator and therelation between speed and frequency
	2 <sup>nd</sup>	Terminology in armature winding and expressions for winding factors (Pitch factor, Distributionfactor).
	3 <sup>rd</sup>	Explain harmonics, its causes and impact onwinding factor.
	4 <sup>th</sup>	E.M.F equation of alternator. (Solve numerical problems).
2 <sup>nd</sup> .	1 <sup>st</sup>	Armature reaction and its effect on emf atdifferent power factor of load.
	2 <sup>nd</sup>	The vector diagram of loaded alternator.(numerical problems)
	3 <sup>rd</sup>	Open circuit test of alternator
	4 <sup>th</sup>	Short circuit test of alternator
3 <sup>rd</sup>	1 <sup>st</sup>	Determination of voltage regulation of Alternatorby direct loading and synchronous impedance method. (Solve numerical problems)
	2 <sup>nd</sup>	Parallel operation of alternator using synchro-scope and dark & bright lamp method.
	3 <sub>rq</sub>	Distribution of load by parallel connectedalternators.
	4 <sup>th</sup>	Determination of voltage regulation of Alternatorby direct loading and synchronous impedance method. (Solve numerical problems)
4 <sup>th</sup>	-, 1 <sup>st</sup>	Parallel operation of alternator using synchro-scope and dark & bright lamp method.
	2 <sup>nd</sup>	Distribution of load by parallel connectedalternators.
	3 <sup>rd</sup>	Constructional feature of Synchronous Motor
	4 <sup>th</sup>	Principles of operation, concept of load angle
	1 <sup>st</sup>	Derive torque, power developed.
	2 <sup>nd</sup>	Effect of varying load with constant excitation.
5 <sup>th</sup>	3 <sup>rd</sup>	Effect of varying excitation with constant load.
	4 <sup>th</sup>	Power angle characteristics of cylindrical rotormotor.
6 <sup>th</sup>	1 <sup>st</sup>	Explain effect of excitation on Armature currentand power factor.

	2 <sup>nd</sup>	Hunting in Synchronous Motor
	3 <sup>rd</sup>	Function of Damper Bars in Synchronous motoreria generator.
	4 <sup>th</sup>	B. with a mothod of starting of Synchronousmotor.
	1 <sup>st</sup>	State application of synchronous motor.
	2 <sup>nd</sup>	
7 <sup>th</sup>	2	Production of rotating magnetic field.
	3 <sup>rd</sup>	Constructional feature of Squirrel cage and Shipfing Mudction
	4 <sup>th</sup>	Working principles of operation of 3-phaseInduction motor.
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	1 <sup>st</sup>	Define slip speed, slip and establish the relationof slip with roto quantities.
	2 <sup>nd</sup>	(本)
		Derive expression for torque during starting andrunning
		conditions and derive conditions for maximum torque.
	'	((numerical problems)
8 <sup>th</sup>	3 <sup>rd</sup>	Torque-slip characteristics.relation between fullload torque and
	1 /4	starting torque
		(numerical problems)
	4 <sup>th</sup>	Establish the relations between Rotor Copperloss, Rotor
		output and Gross Torque and relationship of slip with rotor
		copperloss. (numerical problems)
	1 <sup>st</sup>	Methods of starting and different types of starters used for
		three phase
		Induction motor.
9 <sup>th</sup>	2 <sup>nd</sup>	Explain speed control by Voltage Control, Rotorresistance
	t to the	control, Pole changing, frequency control methods.
	3 <sup>rd</sup>	大学的 100 mm 100
	ath.	Plugging as applicable to three phase inductionmotor.
4.7	4 <sup>th</sup>	Describe different types of motor enclosures.
10 <sup>th</sup>	100 B	Explain principle of Induction Generator and state its applications
	2 <sup>nd</sup>	Ferrari's principle.
	3 <sup>rd</sup>	Double revolving field theory and Cross-field theory to
	4.0	analyze starting torque of 1-phase induction motor.
	4 <sup>th</sup>	Working principle, Torque speed characteristics, performance
		characteristics and application of Split phase motor
	1 <sup>st</sup>	Working principle, Torque speed characteristics
11 <sup>th</sup>		performance characteristics and application of Capacitor
	and	Start motor
	2 <sup>nd</sup>	Working principle, Torque speed characteristics,
		performance characteristics and application of Capacitor
	- rd	start, capacitorrun motor.
	3 <sup>rd</sup>	Working principle, Torque speed characteristics,

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	:	performance characteristics and application of Permanent capacitor type motor.
	4 <sup>th</sup>	Working principle, Torque speed characteristics, performance characteristics and application of Shaded pole motor.
P. 128	1 <sup>st</sup>	Method to change the direction of rotation of above motors.
	2 <sup>nd</sup>	Construction, working principle, running characteristic and application of single phaseseries motor.
12 <sup>th</sup>	3 <sup>rd</sup>	Construction, working principle and application of Universal motors.
	4 <sup>th</sup>	Working principle of Repulsion start Motor,
	1 <sup>st</sup>	Working principle of Repulsion start Induction runmotor.
13 <sup>th</sup>	2 <sup>nd</sup>	Working principle of Repulsion Induction motor.
	3 <sup>rd</sup>	Principle of Stepper motor. Classification of Stepper motor.
	4 <sup>th</sup>	Principle of variable reluctant stepper motor.
	1 <sup>st</sup>	Principle of Permanent magnet stepper motor.
	2 <sup>nd</sup>	Principle of hybrid stepper motor.
14 <sup>th</sup>	3 <sup>rd</sup>	Applications of Stepper motor.
	4 <sup>th</sup>	Construction of Core type, shell type transformer
0.11435	1 <sup>st</sup>	Grouping of winding, Advantages
	2 <sup>nd</sup>	parallel operation of the three phasetransformers.
15 <sup>th</sup>	3 <sup>rd</sup>	tap changer (On/Off load tap changing)
47500	4 <sup>th</sup>	Maintenance Schedule of Power Transformers.

Signature of the Concerned faculty