LESSON PLAN

DEPARTMENT OF MECHANICAL ENGINEERING, GOVT. POLYTECHNIC BHADRK

SUBJECT:- MECHATRONICS

SUBJECT CODE:- TH-4

TOTAL PERIOD:- 60 Period

ACADEMIC YEAR :2022-23

NAME OF THE FACULTY: - SANTANU KUMAR DUTTA (Workshop Superintendent) Theory:- 4p/week

SEMESTER:- 5th

SEM STARTS FROM DATE: 15/09/2022 TO DATE 22/12/2022

NUMBER OF WEEKS:15

			2022 10 DATE 22/12/2022 NOMBER OF WEEKS.15
MONTH	WEEK	DATE/ PERIOD	Syllabus to be covered
	3 RD	15.09.22/1p	1.0 INTRODUCTION TO MECHATRONICS 1.1 Definition of Mechatronics
		17.00.22/1	
		17.09.22/1p	1.2 Advantages & disadvantages of Mechatronics
SEPTEMBER	TH		1.3 Application of Mechatronics
SLI ILWIDLK	4 TH	20.09.2022/	1.4 Scope of Mechatronics in Industrial Sector
		1p	
		21.09.2022	1.5 Components of a Mechatronics System
		22.09.2022/	1.6 Importance of mechatronics in automation
		1p	
	The state of the s	24.09.22/1p	2.0 SENSORS AND TRANSDUCERS
	5 TH	27.09.22/1p	2.1Defination of Transducers
		28.09.22/1p	2.2 Classification of Transducers
		29.09.22/1p	2.3 Electromechanical Transducers
OCTOBER	1 ST	01.10.22/1p	CONTINUED
	3 RD	11.10.22/1p	2.4 Transducers Actuating Mechanisms
		12.10.22/1p	2.5 Displacement &Positions Sensors
		13.10.22/1p	2.6 Velocity, motion, force and pressure sensors.
		15.10.22/1p	2.7 Temperature and light sensors.
	4^{TH}	18.10.22/1p	CONTINUED
	'	19.10.22/1p	3.0ACTUATORS-MECHANICAL, ELECTRICAL
			3.1Mechanical Actuators
		20.10.22/1p	3.1.1 Machine, Kinematic Link, Kinematic Pair
		20.10.22, 19	3.1.2 Mechanism, Slider crank Mechanism
	5 TH	25 10 22/15	<u> </u>
	5	25.10.22/1p	3.1.3 Gear Drive, Spur gear, Bevel gear, Helical gear, worm gear 3.1.4 Belt & Belt drive
			3.1.4 Delt & Delt diffe
		26.10.22/1p	3.1.5 Bearings
		27.10.22/1p	3.2 Electrical Actuator
		29.10.22/1p	3.2.1 Switches and relay
	. COT	0.1.1.2.1.1	3.2.2 Solenoid
NOVEMBER	1 ST	01.11.22/1p	
		2.11.22/1p	3.2.4 A.C Motors
		3.11.22/1p	3.2.5 Stepper Motors
			3.2.6 Specification and control of stepper motors
		5 11 00 /I	
		5.11.22/1p	3.2.7 Servo Motors D.C & A.C
	2 ND	09.11.22/1p	4.0PROGRAMMABLE LOGIC CONTROLLERS(PLC)
			4.1Introduction
		10.11.22/1p	CONTINUED
		12.11.22/1p	4.2Advantages of PLC
	3 RD	15.11.22/1p	CONTINUED
		16.11.22/1p	4.3Selection and uses of PLC
		17.11.22/1p	CONTINUED
		19.11.22/1p	4.4Architecture basic internal structures
	4 TH	22.11.22/1p	CONTINUED
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		23.11.22/1p	4.5Input/output Processing and Programming
		24.11.22/1p	CONTINUED
		26.11.22/1p	CONTINUED
	5 TH	29.11.22/1p	4.6Mnemonics
		30.11.22/1p	CONTINUED
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DECEMBER	1 ST	1.12.22/1p	4.7Master and Jump Controllers
	_	03.12.22/1p	CONTINUED
	2 ND	06.12.22/1p	5.0 ELEMENTS OF CNC MACHINES
	_		5.1 Introduction to Numerical Control of machines and CAD/CAM
		07.12.22/1p	5.1.1 NC machines
		08.12.22/1p	5.1.2 CNC machines
		10.12.22/1p	5.1.3.CAD/CAM
			5.1.3.1 CAD
			5.1.3.2 CAM
	3 RD	13.12.22/1p	CONTINUED
		14.12.22/1p	5.1.3.3 Software and hardware for CAD/CAM
		15.12.22/1p	5.1.3.4 Functioning of CAD/CAM system
		17.12.22/1p	5.1.3.4 Features and characteristics of CAD/CAM system
	4 TH	20.12.22/1p	5.1.3.5 Application areas for CAD/CAM
		21.12.22/1p	5.2 elements of CNC machines
			5.2.1 Introduction
		22.12.22/1p	5.2.2 Machine Structure
		24.12.22/1p	5.2.3 Guideways/Slide ways
		Extra Class	5.2.3.1 Introduction and Types of Guideways
			5.2.3.2 Factors of design of guideways
		Extra Class	5.2.4 Drives
			5.2.4.1Spindledrives
			5.2.4.2 Feed drive
		Extra Class	5.2.5 Spindle and Spindle Bearings
		Extra Class	6.0 ROBOTICS