

LESSON PLAN

SUB: MECHATRONIC

BRANCH:- MECHANICAL ENGG.

SEMESTER: 5TH

NAME OF FACULTY: ER. BIKASH MURMU



**GOVERNMENT POLYTECHNIC,
BHADRAK**


SESSION:2025-26

Hod ,Mechanical

Academic Co-ordinator
Academic Co-ordinator

Principal
Govt. Polytechnic, Bhadrak

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| Discipline: <u>MECHANICAL</u> | Semester: <u>5th</u> | Name of the Teaching Faculty: BIKASH MURMU, SR. LECTURER |
| Subject: mechatronic | No. of days/per week class allotted: 4 | Semester From date: 14/07/2025 To date: 15-11-25 No of weeks: 15 |
| Week | Class Day | Theory Topics: |
| 1st | 1st | INTRODUCTION: 1 Definition of Mechatronics |
| | 2nd | Advantages & disadvantages of Mechatronics |
| | 3rd | Application of Mechatronics |
| | 4th | Scope of Mechatronics in Industrial Sector |
| 2nd | 1st | Components of a Mechatronics System |
| | 2nd | Importance of mechatronics in automation |
| | 3rd | SENSORS AND TRANSDUCERS |
| | 4th | Defination of Transducers |
| 3rd | 1st | Classification of Transducers |
| | 2nd | Electromechanical Transducers |
| | 3rd | Transducers Actuating Mechanisms |
| | 4th | Displacement & Positions Sensors |
| 4th | 1st | Velocity, motion, force and pressure sensors |
| | 2nd | Temperature and light sensors. |
| | 3rd | ACTUATORS-MECHANICAL, ELECTRICAL |
| | 4th | 1 Mechanical Actuators |
| 5th | 1st | Machine, Kinematic Link, Kinematic Pair |
| | 2nd | Mechanism, Slider crank Mechanism |
| | 3rd | Gear Drive, Spur gear, Bevel gear, Helical gear, worm gear |
| | 4th | Belt & Belt drive |


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| 6 th | 1 st | Bearings , Electrical Actuator) |
| | 2 nd | Switches and relay , Solenoid , D.C Motors |
| | 3 rd | A.C Motors ,Stepper Motors |
| | 4 th | Specification and control of stepper motors Servo Motors D.C & A.C. |
| 7 th | 1 st | Revision of Chapter-II |
| | 2 nd | PROGRAMMABLE LOGIC CONTROLLERS(PLC): 1 Introduction |
| | 3 rd | Advantages of PLC |
| | 4 th | Selection and uses of PLC. |
| 8 th | 1 st | Architecture basic internal structures. |
| | 2 nd | Input/output Processing and Programming. |
| | 3 rd | Mnemonics Master and Jump Controllers |
| | 4 th | ELEMENTS OF CNC MACHINES |
| 9 th | 1 st | Introduction to Numerical Control of machines and CAD/CAM |
| | 2 nd | NC machines. |
| | 3 rd | CNC machines |
| | 4 th | 3.CAD/CAM. |
| 10 th | 1 st | CAD ,CAM, |
| | 2 nd | Software and hardware for CAD/CAM |
| | 3 rd | Functioning of CAD/CAM system |
| | 4 th | Features and characteristics of CAD/CAM system |

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| 11 th | 1 st | Application areas for CAD/CAM |
| | 2 nd | elements of CNC machines |
| | 3 rd | Introduction |
| | 4 th | Machine Structure |
| 12 th | 1 st | Guideways/Slide ways. |
| | 2 nd | 1 Introduction and Types of Guideways, |
| | 3 rd | Factors of design of guideways |
| | 4 th | Spindle drives |
| 13 th | 1 st | Feed drive |
| | 2 nd | Spindle and Spindle Bearings |
| | 3 rd | Revision class ch-3 |
| | 4 th | Definition, Function and laws of robotics |
| 14 th | 1 st | Types of industrial robots. |
| | 2 nd | Robotic systems |
| | 3 rd | Advantages and Disadvantages of robots |
| | 4 th | Revision-chapter-4 |
| 15 th | 1 st | DISCUSSION OF PYQ |
| | 2 nd | Revision-chapter-5 |
| | 3 rd | DISCUSSION OF PYQ |
| | 4 th | DISCUSSION OF PYQ |

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